Image-Segmentation-YOLOv7-Pytorch-GPL-Jupyter

YOLOv7 is the most powerful object detection algorithm now. We also can use it to do instance segmentation instead of Mask R-CNN.

We organized the code so that we can use JupyterLab to perform the training and inference steps easily.

Version 20230223

Applications

• The YOLOv7 segmentation can be applied to factory defect detection, medical image analysis, biological image analysis, industrial safety image analysis, etc.



How to use

The main process is:

Annotate images -> Prepare files for training -> Training -> Inference

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Name	Last Modified
🖿 data	2 days ago
src src	2 days ago
1_annotation_labelme_json.ipynb	2 days ago
2_convert_yolo_format.ipynb	2 days ago
3_prepare_train_val_txt.ipynb	2 days ago
4_delete_log.ipynb	7 days ago
🗖 5_train.ipynb	a day ago
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1_annotation_labelme_json.ipynb

Open the web page for image annotation.

ipynb parameter:

- "port" is the port used by the web page. If the port is occupied by other program, please change another port value by yourself.
- "dataset" is the dataset name



2_convert_yolo_format.ipynb

Convert the labelme json label file to the yolo format. Before running, please confirm label.names under the label_file path in #parameters and whether the content filled in the category is correct.

Remark:

The content of label.names is the category name without background.

Iabel	.names - No	tepad					_	×
File Edi	t Format	View	Help					
nucleu:	5							~ ~ ~ ~ ~
	Ln 2, Col 1			100%	Windows	(CRLF)	UTF-8	:

3_prepare_train_val_txt.ipynb

Generate training and validation image path files train.txt and val.txt.

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data, data, data, data, data, data, data, data, data,	/nucleus/trai /nucleus/trai /nucleus/trai /nucleus/trai /nucleus/trai /nucleus/trai /nucleus/trai /nucleus/trai	n/images/nucleus-: n/images/nucleus-: n/images/nucleus-: n/images/nucleus-: n/images/nucleus-: n/images/nucleus-: n/images/nucleus-: n/images/nucleus-:	L.png L0.png L1.png L2.png L3.png 2.png 3.png 3.png 3.png 3.png		^



4_delete_log.ipynb

Delete the log files from previous training.

Set training related files

Set the content of the yolov7-seg.yaml and coco.yaml files in the dataset, set the name of the data set, the number of categories and the name.



5_train.ipynb

Start training.

ipynb parameter:

- batch_size : batch size of training
- img_size: training image size
- dataset: dataset name to train
- yaml_file: the location of the coco.yaml file used for training
- cfg_file: yolov7-seg.yaml file location for training
- weights_file: the path of the pretrained model used, None means not to use the pretrained model for training
- device: GPU ID used for training
- hypFile: hyp.scratch-high.yaml file location for training
- save_model_path: save the location of the model file generated by training
- log_path: The location of the tensorbaord log file where the training is stored
- epochs: number of training epochs

AutoAnchor: 4.50 anchors/target, 1.000 Best Possible Recall (BPR). Current anchors are a good fit to dataset Plotting labels to data\nucleus\model\labels.jpg... Image sizes 512 train, 512 val Using 8 dataloader workers Logging results to data\nucleus\model Starting training for 3000 epochs...

	Class	Images	Instances	Box(P	R	mAP50	mAP50-95)	Mask(P	R	mAP		
	all	9	11	0	0	0	0	0	0		0	0
Epoch	GPU_mem	box_loss	seg_loss	obj_loss	cls_loss	Instances	Size					
1/2999	5.58G	0.1213	0.4159	0.0179	0	36	512:	100%	1/1	[00:00<0		
	Class	Images	Instances	Box(P	R	mAP50	mAP50-95)	Mask(P	R	mAP		
	all	9	11	0	0	0	0	0	0		0	0
Epoch	GPU_mem	box_loss	seg_loss	obj_loss	cls_loss	Instances	Size					
2/2999	5.58G	0.118	0.3186	0.01787	0	26	512:	100%	1/1	[00:00<0		
	Class	Images	Instances	Box(P	R	mAP50	mAP50-95)	Mask(P	R	mAP		
	all	9	11	0	0	0	0	0	0		0	0
Epoch	GPU mem	box loss	seg loss	obj loss	cls loss	Instances	Size					
3/2999	5.58G	0.1196	0.2178	0.01485	0	20	512:	100%	1/1	[00:00<0		
	Class	Images	Instances	Box(P	R	mAP50	mAP50-95)	Mask(P	R	mAP		
	all	9	11	0	0	0	0	0	0		0	0

6_tensorboard.ipynb

You can view the training loss curve and other related information by using TensorBoard.

import os										
<pre>res = os.system('taskkill /IM "tensorboard.exe" /F') res = os.system('del /q %TMP%\.tensorboard-info*')</pre>										
%load_ext tensorboard										
# If timeout, please execute "Kernel -> Restart Kernal and Run All Cells".										
tensorboardlogdir=data/nucleus/lo	ogs/port 6006									
TensorBoard SCALARS	IMAGES TIME SERIES		() UPLOAD	¢ c	\$ ⑦					
Show data download links	Q Filter tags (regular exp	ressions supported)								
Tooltip sorting method:	metrics				8 ^					
Smoothing 0.6	MAP_0.5(B) tag: metrics/mAP_0.5(B) 6e-3 5e-3 4e-3									
Horizontal Axis STEP RELATIVE WALL Image: Constraint of the second sec	3e-3 2e-3 1e-3 0 0 2 4	6 8 10 12 14								
Runs Write a regex to filter runs	mAP_0.5(M) tag: metrics/mAP_0.5(M)									
TOGGLE ALL RUNS	4e-3 3e-3									

7_inference_image.ipynb

Infer one single image.

ipynb parameter:

- dataset is the dataset name.
- source is the inferred image path.
- weights_file is the inference model path.

dataset = "nucleus"
source = "data/%s/test/images/nucleus-14.png" %(dataset)
image_size = 512

weights_file = "data/%s/model/best.pt" %(dataset)
device = "0"
threshold = 0.5

%run src/segment/predict.py --source \$source --imgsz \$image_size \$image_size --weights \$weights_file --conf-thres \$threshold --device

segment\predict: weights=['data/nucleus/model/best.pt'], source=data/nucleus/test/images/nucleus-14.png, data=src\data\coco128.yaml, imgsz=[512, 512], conf_thres=0.5, iou_thres=0.45, max_det=10000, device=0, view_img=True, save_txt=False, save_conf=False, save_crop=F alse, nosave=True, classe=None, agnostic_nms=False, augment=False, visualize=False, update=False, project=data/nucleus, name=, exist _ok=True, line_thickness=3, hide_labels=False, hide_conf=False, half=False, dnn=False, show_rate=False, save_plt=False YOLOVS 2022-10-5 Python-3.9.12 torch-1.12.0+cu113 CUDA.10 (NVIDIA TITAN RTX, 24576MiB)

Fusing layers...

yolov7-seg summary: 325 layers, 37842476 parameters, 0 gradients Single: nucleus center point: (260,282), pixel count = 21875 Total: nucleus pixel count = 21875



nucleus, count=21875 nucleus, single count=21875

8_inference_image_folder_1.ipynb

Infer all images in the folder.

ipynb parameter:

- dataset is the dataset name.
- source is the inferred image path.
- weights_file is the inference model path.

source = "data/%s/test/images" %(dataset) image_size = 512 weights_file = "data/%s/model/best.pt" %(dataset) device = "0" threshold = 0.5 %run src/segment/predict.py --source \$source --imgsz \$image_size \$image_size --weights \$weights_file --project data/\$dataset --name segment\predict: weights=['data/nucleus/model/best.pt'], source=data/nucleus/test/images, data=src\data\coco128.yaml, imgsz=[512, 51 2], conf thres=0.5, iou thres=0.45, max det=1000, device=0, view img=True, save txt=False, save conf=False, save crop=False, nosave=T rue, classes=None, agnostic_nms=False, augment=False, visualize=False, update=False, project=data/nucleus, name=, exist_ok=True, line _thickness=3, hide_labels=False, hide_conf=False, half=False, dnn=False, show_rate=True, save_plt=False YOLOV5 2022-10-5 Python-3.9.12 torch-1.12.0+cu113 CUDA:0 (NVIDIA TITAN RTX, 24576MiB) Fusing layers... yolov7-seg summary: 325 layers, 37842476 parameters, 0 gradients Single: nucleus center point: (260,282), pixel count = 21875 Total: nucleus pixel count = 21875 nucleus-14



Underkill Rate: 0(0.00%), Overkill Rate: 0(0.00%), Right Rate: 1(100.00%), Total: 1

dataset = "nucleus"

nucleus, count=21875 nucleus, single count=21875

9_inference_webcam.ipynb

Infer the image of the webcam. Press "q" on the display to turn the webcam off.

Reference

- Please refer to the readme.txt in the SDK folder.
- LEADERG AppForAI: https://www.leaderg.com/appforai-windows
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